

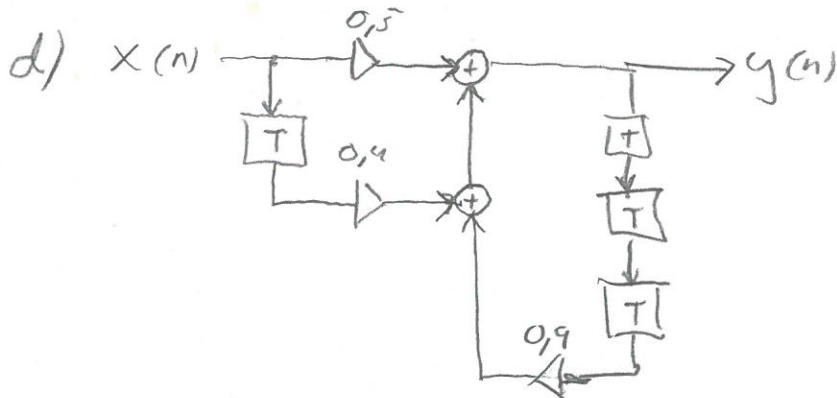
Linear systems exam 151029 - SOLUTIONS

1a) FIR, causal: $H(z) = \sum_{n=0}^N h(n)z^{-n} = \frac{\sum_{n=0}^N h(n)z^{N-n}}{z^N}$

$\Rightarrow N$ poles at $z=0$

b) Periodic sequence and DFT over one or several periods

c) $H(z) = 1+z \Leftrightarrow y(n) = x(n) + x(n+1) \therefore$ Noncausal



e) $x(n) = \delta(n) \Rightarrow y(n) = \delta(n) \therefore$ Time-varying syst.
 $x(n-1) = \delta(n-1) \Rightarrow y(n) = 0$

2a) $H(z) = \frac{z}{z+0,4} + \frac{2,5}{z-0,5} = \frac{z^2 + 2z + 1}{(z+0,4)(z-0,5)} = \frac{(z+1)^2}{(z+0,4)(z-0,5)}$

2 zeros at $z=-1$, poles at $z=-0,4$ & $z=0,5 \therefore$ stable $-0,4 < 1$
 $0,5 < 1$

b) $ROC \stackrel{|z|>}{\text{max}} (-0,4, 0,5) = 0,5$

c) $H(z) = \frac{1 + 2z^{-1} + z^{-2}}{1 - 0,1z^{-1} - 0,2z^{-2}} \Leftrightarrow y(n) - 0,1y(n-1) - 0,2y(n-2) = x(n) + 2x(n-1) + x(n-2)$

d) $h(n) = h_1(n) + h_2(n)$

\downarrow \downarrow
 $= (-0,4)^n u(n) = 2,5 \cdot 0,5^{n-1} u(n-1)$

$$3) y(n) = y_1(n) + y_2(n) + y_3(n)$$

$$y_1(n) : X_1(z) = 2\delta(n) \rightarrow y_1(n) = 2 \cdot h(n) = 2 \cdot (-0,1)^n u(n)$$

$$y_2(n) : X_2(z) = \delta(n-1) \rightarrow y_2(n) = h(n-1) = 2 \cdot (-0,1)^{n-1} u(n-1)$$

$$y_3(n) : Y_3(z) = H(z) X_3(z) = \frac{2}{2+0,1} \cdot z^{-2} \cdot \frac{2}{2-0,4}$$

$$= 2^{-2} \cdot \left(\frac{0,22}{2+0,1} + \frac{0,82}{2-0,4} \right)$$

$$\Rightarrow y_3(n) = (0,2 \cdot (-0,1)^{n-2} + 0,8 \cdot (0,4)^{n-2}) u(n-2)$$

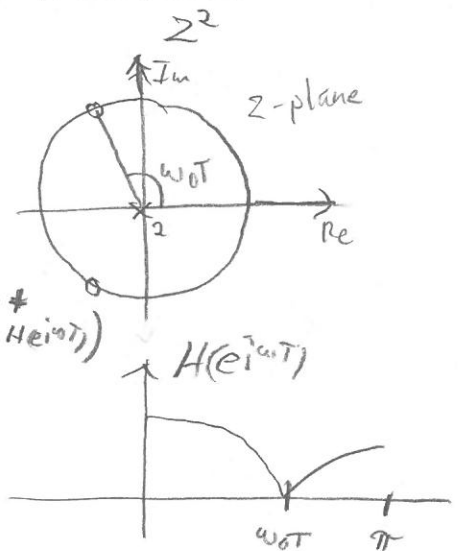
$$4) H(z) = \zeta \cdot (1 - 2\cos(\omega_0 T)z^{-1} + z^{-2})$$

$$= \zeta \cdot \frac{(z^2 - 2\cos(\omega_0 T)z + 1)}{z^2} = \zeta \cdot \frac{(z - e^{j\omega_0 T})(z - e^{-j\omega_0 T})}{z^2}$$

zeros at $\omega T = \pm \omega_0 T \Leftrightarrow z = e^{\pm j\omega_0 T}$

\Rightarrow the term $3\sin(0,8\pi n)$ eliminated
if $\omega_0 T = 0,8\pi$ since $\sin(\omega n) \rightarrow$

$$|H(e^{j\omega T})| \cdot \sin(\omega n + \arg H(e^{j\omega T}))$$



$\omega T = 0,2\pi$:

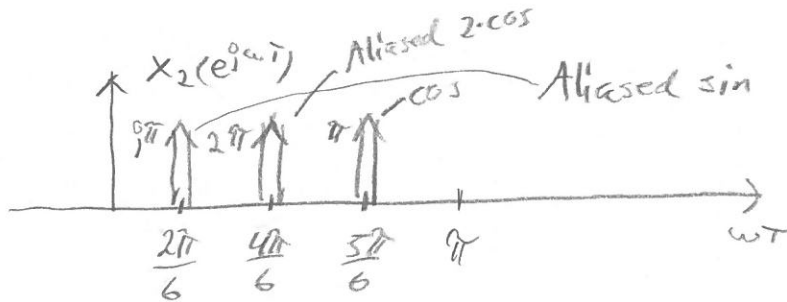
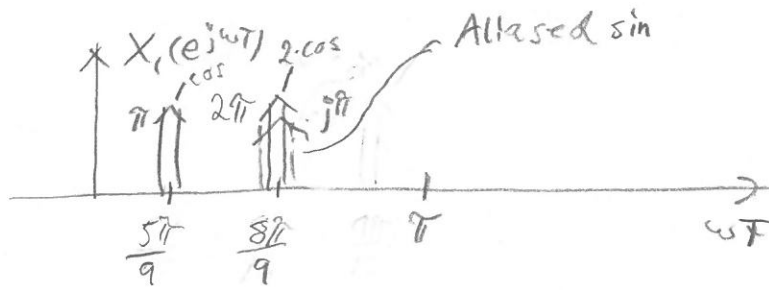
$$|H(e^{j\omega T})| = \zeta \cdot |1 - 2\cos(\omega_0 T)e^{-j\omega T} + e^{-j2\omega T}|$$

$$= \zeta \cdot |2 \cdot \cos(\omega T) - 2\cos(\omega_0 T)|$$

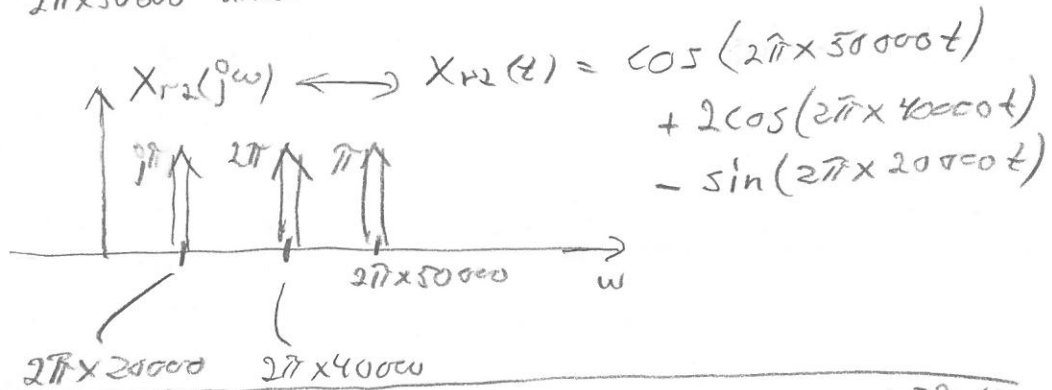
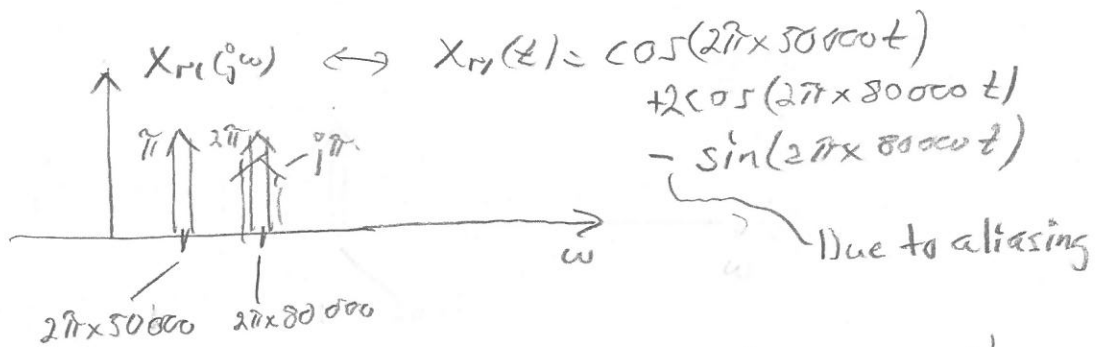
$$= |_{\omega T = 0,2\pi, \omega_0 T = 0,8\pi} = 2 \cdot \zeta \cdot |\cos(0,2\pi) - \cos(0,8\pi)|$$

$$\stackrel{\substack{+1 \\ -2 \\ \uparrow \\ \text{Desired}}}{\zeta}}{\Rightarrow} \zeta = \pm \frac{1}{4(\cos(0,2\pi) - \cos(0,8\pi))} \approx \pm 0,1545$$

5a)



b)



$$6) X(n) = 2 + \cos(0,625\pi n + 0,2) = 2 + \frac{e^{j0,2}}{2} \cdot e^{j\frac{2\pi \cdot 10}{32} \cdot n} + \frac{e^{-j0,2}}{2} \cdot e^{j\frac{2\pi \cdot 22}{32} \cdot n}$$

$$= \frac{1}{32} \sum_{k=0}^{31} X_1(k) e^{j\frac{2\pi k}{32} \cdot n}$$

$$\Rightarrow X_1(k) = \begin{cases} 64 & k=0 \\ 16 e^{j0,2} & k=10 \\ 16 e^{-j0,2} & k=22 \\ 0 & \text{otherwise} \\ 0 \leq k \leq 31 \end{cases}$$

$$|X_1(k)| = \begin{matrix} k=0 & 10 & 22 \\ 64 & 16 & 16 \end{matrix}$$

$$\arg\{X_1(k)\} = \begin{matrix} k=0 & 10 & 22 \\ 0 & 0,2 & -0,2 \end{matrix}$$

$|X_1(k)|$ zero otherwise

$\arg\{X_1(k)\}$ undefined otherwise

